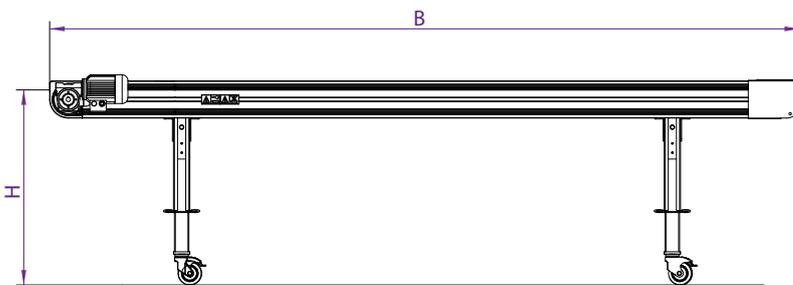
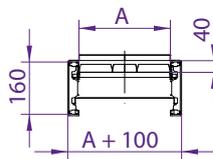


technical features

- Structure made of aluminium anodised profile height 160 mm
- With side panel not removable height 40 mm
- White plastic belt, without slats. Plastic belt complete with special double containment edges, which do not open even during the rotation of the belt itself
- Transmission group composed of: three-phase motor, worm reduction unit with lubrication for life and safety limiter
- Fixed standard speed ~4 m/min
- Equipped with Start/Stop motor cut-out
- Standard motor supply voltage 400V/50 Hz



required dimensions

A (mm) _____

B (mm) _____

H (mm) _____

capacity Kg _____

material to convey _____

specify presence of
lubrificant colorant or
or other fluid
if present _____

NOTE

optional

SUPPORTING LEGS

- with rotative wheels and brake
- with antivibrating feet
- with both rotative wheels and antivibrating feet
- without supporting legs

CONTAINMENT EDGES

- with special edges h _____ mm
- with adjustable edges in width _____ mm /
in height _____ mm

CONVEYOR PLASTIC BELT

- standard plastic belt slightly high grip without slats
- standard plastic belt slightly high grip with slats
h 35 mm and pitch _____ mm
- special perforated plastic belt designed
for cooling systems

TRANSMISSION GROUP

- mounted on the RIGHT side

CONTROL PANEL - REQUIRED FUNCTIONS

- START / STOP (standard)
- INVERTER
independently from the functions programmed in the control panel, it is always possible to adjust the conveyor speed
- ROBOT - PULSE
a clean signal coming from the Robot decides the Start of the conveyor. When the running time is over the control panel stops the conveyor and waits for the next signal to repeat the cycle. The panel is complete with a plug for its connection to the external signal
- FEEDER
a clean signal coming from the Robot decides the Start of the conveyor. The conveyor runs for the duration of the signal coming from the Robot. The panel is complete with a plug for its connection to the external signal
- PAUSE - WORK
programming the control board in this function, it is possible to set the conveyor's STOP and WORK time, causing his intermittent advancing, independently from any external signal